

ABSTRACT

A driving-operation assist is characterized by comprising:

circumferential-state imaging means for imaging a circumferential state of a vehicle with a camera and generating a circumferential-state image;

synthetic-image generating means for generating a synthetic image by superimposing on the circumferential-state image, an assumed-movement pattern which is the video data showing movement of the vehicle in case of performing a predetermined series of driving operations for the vehicle; and

displaying means for displaying the synthetic image, and

the circumferential-state imaging means has one camera or more and a camera parameter table for storing a camera parameter which is a characteristic of the camera or each of the cameras and generates the circumferential-state image on the basis of the camera parameter from an output of the camera or each of the cameras.

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